

E80H Series Incremental Ø80mm Hollow Shaft Type

Hollow Shaft Type Ø80mm Incremental Rotary Encoder

■ Features

- Ø80mm, Inner diameter of shaft Ø30mm, Ø32mm
- No coupling needed with direct installation at motor or rotation shaft of machine
- Power supply: 5VDC, 12-24VDC ±5%
- Various output types

 Please read "Safety Considerations" in operation manual before using.



■ Ordering Information

E80H	30	—	3200	—	3	—	N	—	24	—	
Series	Shaft diameter		Pulses/revolution		Output phase		Control output		Power supply		Cable
Ø80mm, hollow shaft type	30: Ø30mm 32: Ø32mm		60, 100, 360, 500, 512, 1024, 3200		3: A, B, Z 6: A, $\bar{A}$, B, $\bar{B}$, Z, $\bar{Z}$		T: Totem pole output N: NPN open collector output V: Voltage output L: Line driver output		5: 5VDC ±5% 24: 12-24VDC ±5%		No mark: Radial cable type C: Radial cable connector type

■ Specifications

Item		Hollow Shaft Type Ø80mm Incremental Rotary Encoder		
Resolution (PPR) ^{※1}		60, 100, 360, 500, 512, 1024, 3200		
Electrical specification	Output phase		A, B, Z phase (line driver output A, $\bar{A}$, B, $\bar{B}$, Z, $\bar{Z}$ phase)	
	Phase difference of output		Output between A and B phase: $\frac{T}{4} \pm \frac{T}{8}$ (T=1 cycle of A phase)	
	Control output	Totem pole output	• [Low] - Load current: max. 30mA, residual voltage: max. 0.4VDC= • [High] - Load current: max. 10mA, Output voltage (power voltage 5VDC=): min. (power voltage-2.0)VDC= Output voltage (power voltage 12-24VDC=): min. (power voltage-3.0)VDC=	
		NPN open collector output	Load current: max. 30mA, residual voltage: max. 0.4VDC=	
		Voltage output	Load current: max. 10mA, residual voltage: max. 0.4VDC=	
		Line driver output	• [Low] - Load current: max. 20mA, residual voltage: max. 0.5VDC = • [High] - Load current: max. -20mA, Output voltage (power voltage 5VDC=): min. 2.5VDC= Output voltage (power voltage 12-24VDC=): min. (power voltage-3.0)VDC=	
	Response time (rise, fall)	Totem pole output	Max. 1μs (cable length: 2m, I sink = 20mA)	
		NPN open collector output		
		Voltage output		
		Line driver output		
	Max. response frequency		200kHz	
	Power supply		• 5VDC= ±5% (ripple P-P: max. 5%) • 12-24VDC= ±5% (ripple P-P: max. 5%)	
Current consumption		Max. 80mA (disconnection of the load), Line driver output: max. 50mA (disconnection of the load)		
Insulation resistance		Over 100MΩ (at 500VDC megger between all terminals and case)		
Dielectric strength		750VAC 50/60Hz for 1 minute (between all terminals and case)		
Connection		Radial cable type, Radial cable connector type		
Mechanical specification	Starting torque		Max. 200gf·cm (0.0196N·m)	
	Moment of inertia		Max. 800g·cm ² (8×10 ⁻⁵ kg·m ²)	
	Shaft loading		Radial: max. 5kgf, Thrust: max. 2.5kgf	
	Max. allowable revolution ^{※2}		3,600rpm	
Vibration		1.5mm amplitude at frequency of 10 to 55Hz (for 1 min) in each X, Y, Z direction for 2 hours		
Shock		Approx. max. 75G		
Environment	Ambient temperature		-10 to 70°C, storage: -25 to 85°C	
	Ambient humidity		35 to 85%RH, storage: 35 to 90%RH	
Protection structure		IP50 (IEC standard)		
Cable		Ø5mm, 5-wire (line driver output: 8-wire), 2m, Shield cable (AWG24, core diameter: 0.08mm, number of cores: 40, insulator out diameter: Ø1mm)		
Accessory		Spring bracket		
Approval		CE (except for line driver output)		
Unit weight		Approx. 560g		

※1: Not indicated resolutions are customizable.

※2: Make sure that max. response revolution should be lower than or equal to max. allowable revolution when selecting the resolution.

$$[\text{Max. response revolution (rpm)}] = \frac{\text{Max. response frequency}}{\text{Resolution}} \times 60 \text{ sec}$$

※Environment resistance is rated at no freezing or condensation.

(A) Photoelectric Sensors

(B) Fiber Optic Sensors

(C) Door/Area Sensors

(D) Proximity Sensors

(E) Pressure Sensors

(F) Rotary Encoders

(G) Connectors/ Connector Cables/ Sensor Distribution Boxes/Socket

(H) Temperature Controllers

(I) SSRs / Power Controllers

(J) Counters

(K) Timers

(L) Panel Meters

(M) Tacho / Speed / Pulse Meters

(N) Display Units

(O) Sensor Controllers

(P) Switching Mode Power Supplies

(Q) Stepper Motors & Drivers & Controllers

(R) Graphic/ Logic Panels

(S) Field Network Devices

(T) Software

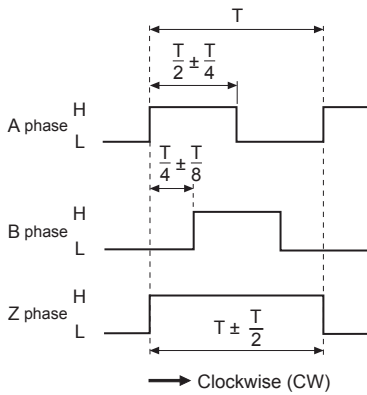
Control Output Diagram

Totem pole output		NPN open collector output	
Rotary encoder circuit	Load Connection	Rotary encoder circuit	Load Connection
Voltage output		Line driver output	
Rotary encoder circuit	Load Connection	Rotary encoder circuit	Load Connection

- All output circuits of A, B, Z phase are same. (line driver output is A, $\bar{A}$, B, $\bar{B}$, Z, $\bar{Z}$)
- Totem pole output type can be used for NPN open collector type (×1) or voltage output type (×2).

Output Waveforms

⊙ Totem pole output /
NPN open collector output /
Voltage output



⊙ Line driver output

