



# A Relational Separation Logic for Effect Handlers

*joint work with  
presented by  
on the*

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**Goal.** Design of a *relational separation logic* for *effect handlers*.

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In short, a *relational separation logic* consists of  
an *assertion language*, to specify programs;  
and a set of *proof rules*, to verify programs compositionally.

The *key* feature is the *refinement relation*, to assert that  $e_s$  is a correct abstraction of  $e_i$ :

$$e_i \lesssim_{\{R\}} e_s \triangleq \text{“if } e_i \text{ terminates with value } v_i, \text{ then } e_s \text{ terminates with a value } v_s \text{ s.t. } R(v_i, v_s)\text{”}$$

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## Applications.

- **Program Verification & Program Reasoning.**  
To *specify* and *understand* a program in terms of a *simpler implementation*.
- **Compiler Optimisations.**  
An optimisation is *correct* if the *optimised program* does *not* introduce *behaviours*.
- **Type Systems.**  
To show *soundness* and *abstraction properties* of type systems.

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## Example

A *relational separation logic* allows an *effect-handler-based* implementation of *concurrency* to be explained in terms of a *direct* implementation:

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effect Fork : (unit -> unit) -> unit
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It formalises the intuition, that, under this handler, an effect `Fork` can be seen as `fork` itself:

$$\text{perform (Fork f)} \quad \lesssim \quad \text{fork (f ())}$$

The *meaning* of an *effect* depends on a *handler*.

## 1. Definition of the Refinement Relation.

The standard refinement relation does not *specify* the case of *effects*:

$e_i \lesssim e_s \{R\} \triangleq$  “if  $e_i$  terminates with value  $v_i$ , then  $e_s$  terminates with a value  $v_s$  s.t.  $R(v_i, v_s)$ ”

## 2. Compositional Reasoning (Handler vs. Handlee).

How to *reason* about a program that *performs* effects *independently* of its *handler*?

## 3. Context-Local Reasoning.

How to *reason* about a program *independently* of its *evaluation context*?

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```
match main (fun f -> perform (Fork f)) with
| effect (Fork f), k -> h
| _ -> r
  ≈
main (fun f -> fork (f ()))
```

Handlee Part

```
main (fun f -> perform (Fork f)) ≈
main (fun f -> fork (f ()))
```

Handler Part

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$$e_i \lesssim e_s \{y_i, y_s. K_i[y_i] \lesssim K_s[y_s] \{R\}\}$$

(Standard) Bind

$$K_i[e_i] \lesssim K_s[e_s] \{R\}$$

# Key Idea

The *key idea* is to extend the refinement relation with a *parameterised relational theory*, an *axiomatisation* of *relations* that should hold:

$$e_i \lesssim e_s \langle \mathcal{T} \rangle \{R\}$$

The resulting logic is called *baze*; it is built on top of *Iris*.

A *relational theory* is formalised in *Iris* as a *set* of *admitted relations* (on arbitrary expressions):

$$\mathcal{T} : \underbrace{(\text{expr} \times \text{expr})}_{\text{impl.}} \times \underbrace{(\text{expr} \times \text{expr})}_{\text{spec.}} \times \underbrace{((\text{expr} \times \text{expr}) \rightarrow \text{iProp})}_{\text{return condition (postcondition)}} \rightarrow \underbrace{\text{iProp}}_{\text{precondition}}$$

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**Examples.** Empty theory.

$$\perp (e_i, e_s, R) = \text{False}$$

$$e_i \lesssim e_s \{R\} \Leftrightarrow e_i \lesssim e_s \langle \perp \rangle \{R\}$$

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**Examples.** Concurrency effects.

$$\text{FORK}(\text{perform } (\text{Fork } f_i), \mathbf{fork} (f_s ()), R) = \\ \triangleright f_i () \lesssim f_s () \langle \text{FORK} \rangle \{\text{True}\} * R((), ())$$

$$\triangleright f_i () \lesssim f_s () \langle \text{FORK} \rangle \{\text{True}\} \multimap$$

$$\text{perform } (\text{Fork } f_i) \lesssim \mathbf{fork} (f_s ()) \langle \text{FORK} \rangle \{y_i, y_s. y_i = y_s = (())\}$$

## Challenge 1 - Definition of the Refinement Relation in base

**Problem.** The *meaning* of an *effect* depends on a *handler*.

**Solution. (Biorthogonality)** To *universally quantify* over *contexts* that *validate* a *theory*.

Under the hood, the *parameterised refinement relation* unfolds to a *standard refinement* with  $e_i$  and  $e_s$  under *universally quantified contexts*:

$$e_i \lesssim e_s \langle \mathcal{T} \rangle \{R\} \triangleq \forall K_i K_s S. \langle \mathcal{T} \rangle \{R\} K_i \lesssim K_s \{S\} \multimap K_i[e_i] \lesssim K_s[e_s] \{S\}$$

*Definition of the validation of a relational theory  $\mathcal{T}$  by a pair of contexts:*

$$\begin{aligned} \langle \mathcal{T} \rangle \{R\} K_i \lesssim K_s \{S\} &\triangleq \\ (\forall v_i v_s. R(v_i, v_s) \multimap K_i[v_i] \lesssim K_s[v_s] \{S\}) & \\ \wedge & \\ (\forall e_i' e_s'. \underbrace{\mathcal{T} \langle e_i', e_s', R \rangle}_{\approx \mathcal{T}(e_i', e_s', R)} \multimap K_i[e_i'] \lesssim K_s[e_s'] \{S\}) & \end{aligned}$$

## Challenge 2 – Compositional Reasoning (Handler vs. Handlee)

The *exhaustion rule* allows *compositional reasoning* about programs with *effect handlers*.

$$e_i \lesssim e_s \langle \mathcal{T} \rangle \{R\}$$

$$(\forall v_i v_s. R(v_i, v_s) \multimap K_i[v_i] \lesssim K_s[v_s] \langle \mathcal{F} \rangle \{S\})$$

$$\wedge$$
$$(\forall e_i' e_s'. \mathcal{T} \langle e_i', e_s', R \rangle \multimap K_i[e_i'] \lesssim K_s[e_s'] \langle \mathcal{F} \rangle \{S\})$$

---

Exhaustion

$$K_i[e_i] \lesssim K_s[e_s] \langle \mathcal{F} \rangle \{S\}$$

The rule allows one to see the *theory*  $\mathcal{T}$  as a *boundary* between *handlee* and *handler*.

## Challenge 3 – Context-Local Reasoning

The *bind rule* allows *context-local reasoning*:

$$\frac{\text{traversable}(K_i, K_s, \mathcal{T}) \quad e_i \approx e_s \langle \mathcal{T} \rangle \{y_i, y_s. K_i[y_i] \approx K_s[y_s] \langle \mathcal{T} \rangle \{R\}\}}{K_i[e_i] \approx K_s[e_s] \langle \mathcal{T} \rangle \{R\}} \text{ Bind}$$

The *contexts* should be able to “*traverse*” the *relational theory*  $\mathcal{T}$ :

$$\text{traversable}(K_i, K_s, \mathcal{T}) = \text{“The theory } \mathcal{T} \text{ holds regardless of the contexts } K_i \text{ and } K_s\text{.”}$$

## Challenge 3 – Context-Local Reasoning

The *context-closure* of a theory is *traversable by construction*:

$(E_i, E_s) \Downarrow \mathcal{T}$   
└───  
a pair of sets of effects

**Properties.**

1. The *context-closure* of  $\mathcal{T}$  extends  $\mathcal{T}$ :

$$\mathcal{T}(e_i, e_s, R) \multimap ((E_i, E_s) \Downarrow \mathcal{T})(e_i, e_s, R)$$

$K_s$  has no handler for  
an effect in  $E_s$

2. The *context-closure* of  $\mathcal{T}$  is *traversable by neutral contexts*:

$$\text{traversable}(K_i, K_s, ((E_i, E_s) \Downarrow \mathcal{T})) \Leftarrow \text{neutral}(E_i, K_i) \wedge \text{neutral}(E_s, K_s)$$

Under a *context-closed theory*, the *bind rule* can be *simplified* as follows:

$$\frac{\text{neutral}(E_i, K_i) \quad \text{neutral}(E_s, K_s) \quad e_i \lesssim e_s \langle (E_i, E_s) \Downarrow \mathcal{T} \rangle \{y_i, y_s. K_i[y_i] \lesssim K_s[y_s] \langle (E_i, E_s) \Downarrow \mathcal{T} \rangle \{R\}\}}{\text{Derived Bind}}$$

$$K_i[e_i] \lesssim K_s[e_s] \langle (E_i, E_s) \Downarrow \mathcal{T} \rangle \{R\}$$

We can now revisit the refinement between the two implementations of concurrency:

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effect Fork : (unit -> unit) -> unit    ≲    main (fun f -> fork (f ()))
let q = Queue.create () in
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## Key Steps.

1. *Identify* the *theory* to reason about the *Fork effects*:

$([Fork], []) \Downarrow \text{FORK}$

$\text{FORK}(\text{perform } (Fork f_i), \mathbf{fork} (f_s ()), R) =$   
 $\triangleright f_i () \lesssim f_s () \langle \text{FORK} \rangle \{True\} * R((), ())$

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## Key Steps.

1. *Identify* the *theory* to reason about the *Fork effects*:
2. *Apply* the *exhaustion rule* to *decompose* the *proof* into a *handler* part and a *handlee* part:

$$([\text{Fork}], []) \Downarrow \text{FORK}$$
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$$\text{main}(\text{fun } f \rightarrow \text{perform}(\text{Fork } f)) \lesssim \\ \text{main}(\text{fun } f \rightarrow \text{fork}(f ())) \\ \langle \langle [\text{Fork}], [] \rangle \Downarrow \text{FORK} \rangle \{ \text{True} \}$$

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1. *Identify* the *theory* to reason about the *Fork effects*:
2. *Apply* the *exhaustion rule* to *decompose* the *proof* into a *handler* part and a *handlee* part:
3. *Apply* the *bind rule* to *step through* the *verification*.

$([Fork], []) \Downarrow \text{FORK}$

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$\text{main } (\text{fun } f \rightarrow \text{perform } (Fork f)) \lesssim$   
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 $\langle ([Fork], []) \Downarrow \text{FORK} \rangle \{True\}$

# Concurrency

To *verify* the *handler*, we introduce *novel reasoning rules* for *concurrency*:

$$\frac{\forall i. i \ni e_s \multimap e_i \approx K_s[()] \langle \mathcal{T} \rangle \{R\}}{e_i \approx K_s[\mathbf{fork} \ e_s] \langle \mathcal{T} \rangle \{R\}} \text{ Fork-R}$$

$$\frac{i \ni K[e_s] \quad \forall j \ K'. j \ni K'[e_s'] \multimap e_i \approx e_s \langle \perp \rangle \{v_i, \_ . \exists v_s'. j \ni K'[e_s'] * R(v_i, v_s')\}}{e_i \approx e_s' \langle \mathcal{T} \rangle \{R\}} \text{ Thread-Swap}$$

$$\frac{i \ni K_s[e_s] \quad e_i \approx e_s \langle \perp \rangle \{v_i, v_s. i \ni K_s[v_s] \multimap K_i[v_i] \approx e_s' \langle \mathcal{T} \rangle \{R\}\}}{K_i[e_i] \approx e_s' \langle \mathcal{T} \rangle \{R\}} \text{ Logical-Fork}$$

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-----\*

effect (Fork  $f_i$ ),  $k_i \rightarrow h \lesssim K_s[\mathbf{fork} \ (f_s \ ())]$

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$$i \ni f_s ()$$
$$h \lesssim K_s[()]$$

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$i \triangleright f_s ()$

-----\*

`Queue.push ki q; run fi  $\lesssim$  Ks[()]`

$$\frac{i \triangleright K[e_s] \quad \forall j \ K'. j \triangleright K'[e_{s'}] \xrightarrow{*} e_i \lesssim e_s \langle \perp \rangle \{v_i, \_ . \exists v_{s'} . j \triangleright K'[e_{s'}] * R(v_i, v_{s'})\}}{e_i \lesssim e_{s'} \langle \mathcal{T} \rangle \{R\}} \text{ Thread-Swap}$$

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$$j \ni K'[K_s[()]]$$

$$\text{Queue.push } k_i \ q; \text{ run } f_i \lesssim f_s \ ()$$

$$i \ni K[e_s]$$

$$\forall j \ K'. j \ni K'[e_{s'}] \xrightarrow{*} e_i \lesssim e_s \langle \perp \rangle \{v_i, \_ . \exists v_{s'} . j \ni K'[e_{s'}] * R(v_i, v_{s'})\}$$

$$e_i \lesssim e_{s'} \langle \mathcal{T} \rangle \{R\}$$

Thread-Swap

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Logical-Fork

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run  $f_i \lesssim f_s \ ()$

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# Concurrency

To *verify the handler*, we introduce *novel reasoning rules for concurrency*:

$$\frac{\forall i. i \ni e_s \multimap e_i \lesssim K_s[()] \langle \mathcal{T} \rangle \{R\}}{e_i \lesssim K_s[\mathbf{fork} \ e_s] \langle \mathcal{T} \rangle \{R\}} \text{ Fork-R}$$

```
-----*
```

```
let ki = Queue.pop q in continue ki () \lesssim ()
```

$$\frac{i \ni K[e_s] \quad \forall j \ K'. j \ni K'[e_s'] \multimap e_i \lesssim e_s \langle \perp \rangle \{v_i, \_ . \exists v_s'. j \ni K'[e_s'] * R(v_i, v_s')\}}{e_i \lesssim e_s' \langle \mathcal{T} \rangle \{R\}} \text{ Thread-Swap}$$

$$\frac{i \ni K_s[e_s] \quad e_i \lesssim e_s \langle \perp \rangle \{v_i, v_s. i \ni K_s[v_s] \multimap K_i[v_i] \lesssim e_s' \langle \mathcal{T} \rangle \{R\}\}}{K_i[e_i] \lesssim e_s' \langle \mathcal{T} \rangle \{R\}} \text{ Logical-Fork}$$

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$\begin{array}{l} j \ni K'[e_s] \\ \text{continue } k_i () \lesssim e_s \\ \hline \text{continue } k_i () \lesssim () \end{array} \star$
--

$$\frac{\begin{array}{l} i \ni K[e_s] \\ \forall j \ K'. j \ni K'[e_s'] \multimap e_i \lesssim e_s \langle \perp \rangle \{v_i, \_ . \exists v_s'. j \ni K'[e_s'] \star R(v_i, v_s')\} \end{array}}{e_i \lesssim e_s' \langle \mathcal{T} \rangle \{R\}} \text{ Thread-Swap}$$

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continue  $k_i () \lesssim e_s$

-----\*

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$$\frac{i \ni K[e_s] \quad \forall j \ K'. j \ni K'[e_s'] \multimap e_i \lesssim e_s \langle \perp \rangle \{v_i, \_ . \exists v_s'. j \ni K'[e_s'] * R(v_i, v_s')\}}{e_i \lesssim e_s' \langle \mathcal{T} \rangle \{R\}} \text{ Thread-Swap}$$

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# Conclusion

## *In This Talk.*



(Motivation) *Importance* of *relational SL* for program *verification* and *reasoning* (*Fork*).

(Challenge) The *meaning* of an *effect* depends on a *handler*.



(Key Idea) In *baze* (a logic build on top of *Iris*), the *refinement relation* is *parameterised* with a *theory*.

(Compositionality) *baze* allows one to *reason* about effects *independently* of the *handler*.

(Context-Local Reasoning) *baze* enjoys a powerful *context-local* reasoning principle.

(Concurrency) *Refinement* between *handler-based* and *direct* implementations of *concurrency*.  
Introduction of *novel rules* in *relational SL* to *reason* about *thread scheduling*.

# Conclusion

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## In the Paper ([A Relational Separation Logic for Effect Handlers](#)).

(Dynamic Effects) *blaze*, a logic for *dynamic effects* built on top of *baze* (a logic for *static effects*).

(Deep vs. Shallow) Support for both *deep* and *shallow handlers*.

(One-Shot vs. Multi-Shot) Support for both *one-shot* and *multi-shot continuations*.

(Case Studies) *Refinement* between *asynchronous-programming* libraries (*Async* & *Await*);  
*Handler-correctness criteria* in *blaze* for *algebraic effects* (*non-determinism*).

# *Acknowledgements*

Thanks to everyone who contributed to this talk:

Carine Morel, Timéo Arnouts, the members of the Veritas group, and my co-authors.

Thanks also to Amin Timany, who spotted a mistake in slide 15:

the slide incorrectly stated an equivalence ( $\Leftrightarrow$ ) instead of a right-to-left implication ( $\Leftarrow$ ).

# Concurrency - Backup

The *complete* set of the *novel reasoning rules* for *concurrency*:

$$i \ni e_s$$

$$e_i \lesssim e_s \langle \perp \rangle \{True\}$$

$$K_i[()] \lesssim e_s' \langle \mathcal{T} \rangle \{R\}$$

Fork-L

$$K_i[\mathbf{fork} \ e_i] \lesssim e_s' \langle \mathcal{T} \rangle \{R\}$$

$$\forall i. i \ni e_s \multimap e_i \lesssim K_s[()] \langle \mathcal{T} \rangle \{R\}$$

Fork-R

$$e_i \lesssim K_s[\mathbf{fork} \ e_s] \langle \mathcal{T} \rangle \{R\}$$

$$i \ni K[e_s]$$

$$\forall j \ K'. j \ni K'[e_s'] \multimap e_i \lesssim e_s \langle \perp \rangle \{v_i, \_ . \exists v_s'. j \ni K'[e_s'] * R(v_i, v_s')\}$$

Thread-Swap

$$e_i \lesssim e_s' \langle \mathcal{T} \rangle \{R\}$$

$$i \ni K_s[e_s]$$

$$e_i \lesssim e_s \langle \perp \rangle \{v_i, v_s. i \ni K_s[v_s] \multimap K_i[v_i] \lesssim e_s' \langle \mathcal{T} \rangle \{R\}\}$$

Logical-Fork

$$K_i[e_i] \lesssim e_s' \langle \mathcal{T} \rangle \{R\}$$

# Concurrency - Backup

Valid *OCaml 5* implementation:

```
type _ Effect.t += Fork : (unit -> unit) -> unit t

let run main =
  let q = Queue.create () in
  let rec run f =
    match f () with
    | effect (Fork f), k ->
      Queue.push k q;
      run f
    | _ ->
      if not (Queue.empty q) then
        let k = Queue.pop q in continue k ()
  in
  run (fun () -> main (fun f -> perform (Fork f)))
```

# Examples of Relational Theories – Backup

## State.

$$\text{GET}(\text{perform } (\text{Get } ()), !r, R) = \exists x. r \mapsto_s^{1/2} x * (r \mapsto_s^{1/2} x \multimap R(x, x))$$

$$\text{SET}(\text{perform } (\text{Set } y), r := y, R) = r \mapsto_s^{1/2} \_ * (r \mapsto_s^{1/2} y \multimap R(v, v))$$

$$\text{STATE} = \text{GET} \oplus \text{SET}$$

$$r \mapsto_s^{1/2} x \multimap \text{perform } (\text{Get } ()) \lesssim !r \langle \text{STATE} \rangle \{y_i, y_s. y_i = y_s = x * r \mapsto_s^{1/2} x\}$$

$$r \mapsto_s^{1/2} \_ \multimap \text{perform } (\text{Set } y) \lesssim r := y \langle \text{STATE} \rangle \{\_, \_. r \mapsto_s^{1/2} y\}$$

## Non-Determinism (Selected Relations).

$$\text{ASSOC}_1(e_{11} \text{ or } (e_{12} \text{ or } e_{13}), (e_{21} \text{ or } e_{22}) \text{ or } e_{23}, R) = \\ \square R(e_{11}, e_{21}) * \square R(e_{12}, e_{22}) * \square R(e_{13}, e_{23})$$

$$\text{UNIT}_1(e_1 \text{ or fail}, e_2, R) = \square R(e_1, e_2)$$

$$\text{ND} = \text{ASSOC}_1 \oplus \text{UNIT}_1 \oplus \dots$$